

# Adaptive Out-of-Step Protection Based on Wide Area Measurements

Marko Tealane

[TUDelft | TaiTech](#)

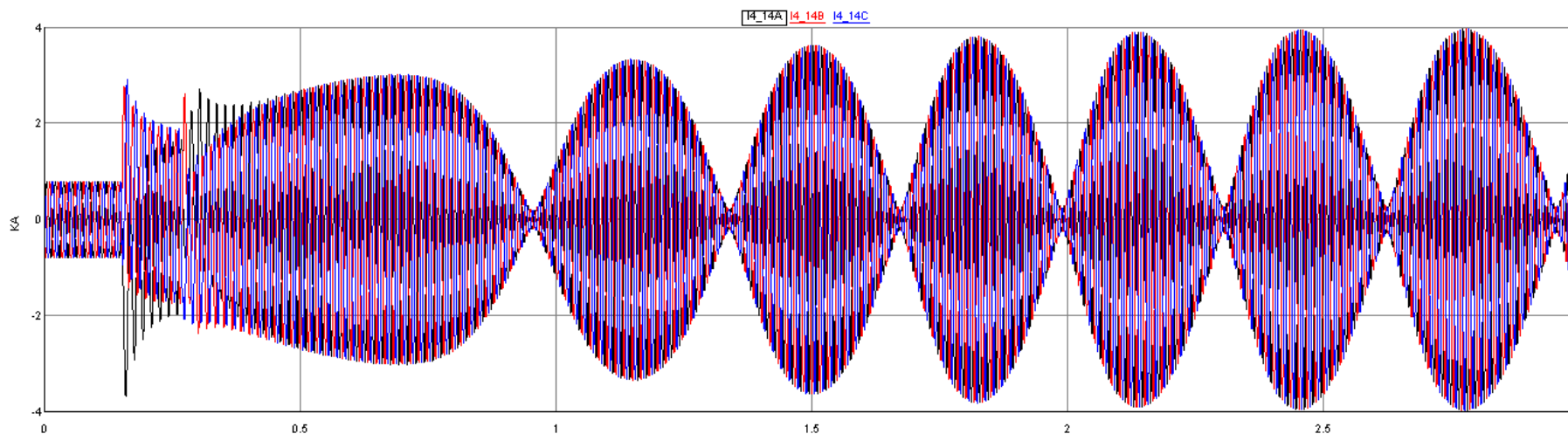


# Outline

- What is an out-of-step condition and conventionally used protection.
- The developed adaptive out-of-step protection concept.
- Hardware-in-the-Loop (HiL) test setup.
- Testing results.

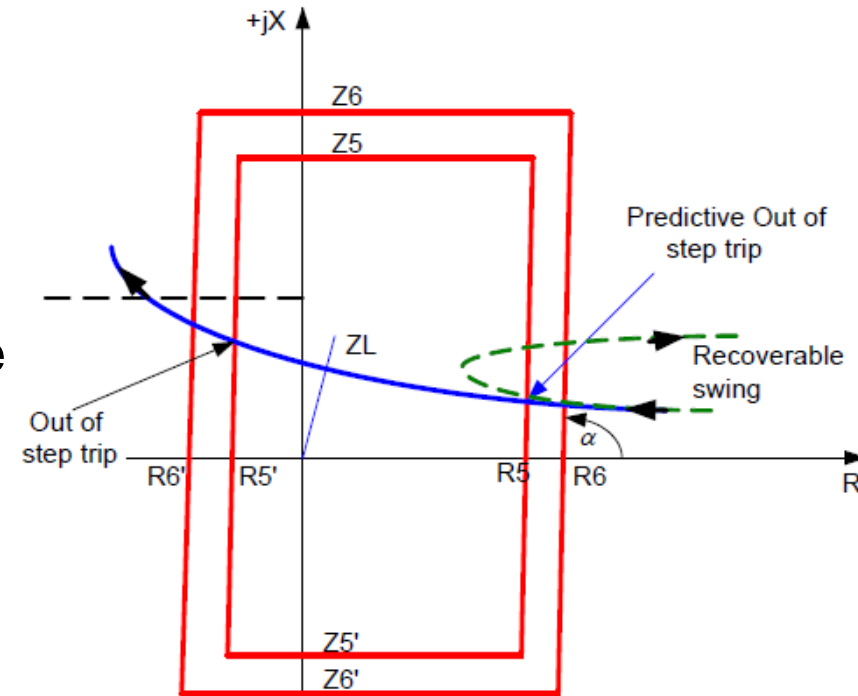
# Out-of-step condition

- What is an out-of-step condition?
- Disturbances can propagate into a larger scale event, causing a major imbalance between the mechanical input and electrical output power of generators. This major imbalance can result in a loss of synchronism in the power system and is referred to as an out-of-step (OOS) condition.
- During the OOS condition large oscillations of currents and voltages occur, which cause additional mechanical and thermal stresses on power system components.



# Out-of-step condition

- Protection?
- The conventional OOS protection is realized by impedance relays which use the apparent impedance seen by the relay to detect an OOS condition.
- These relays require correct settings to function as intended.
- With more renewable energy sources being integrated into the power system, the generator composition becomes harder to predict. This complicates the calculation of settings further.
- A new OOS protection algorithm, using wide-area measurement is proposed and tested.



# The developed adaptive algorithm

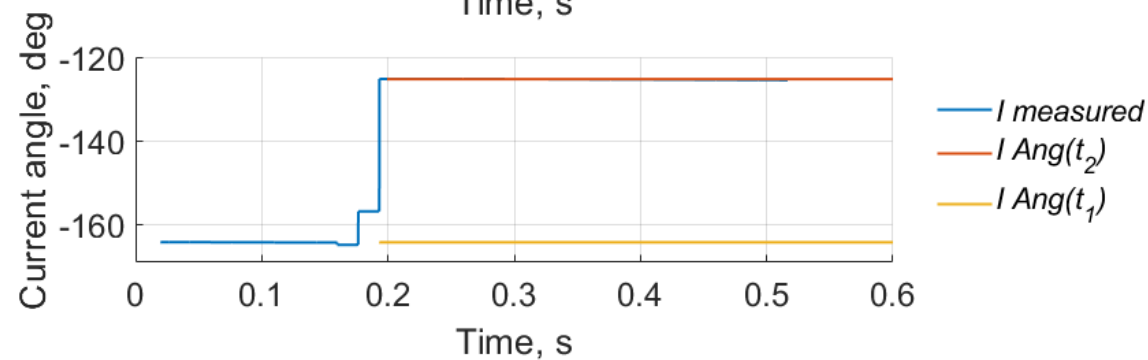
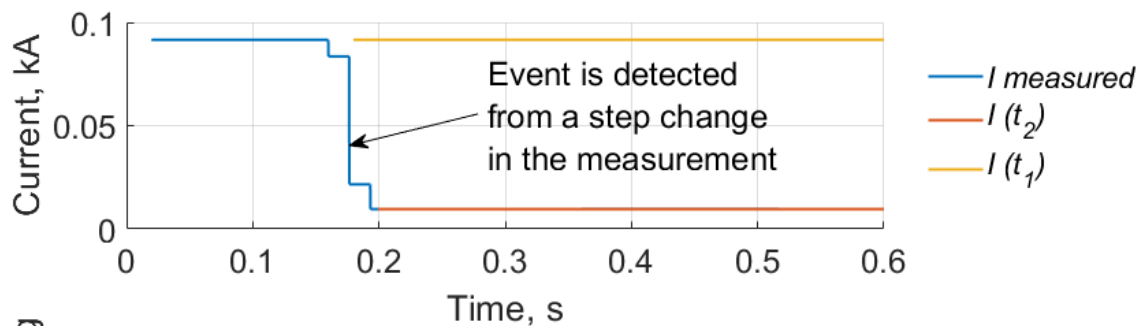
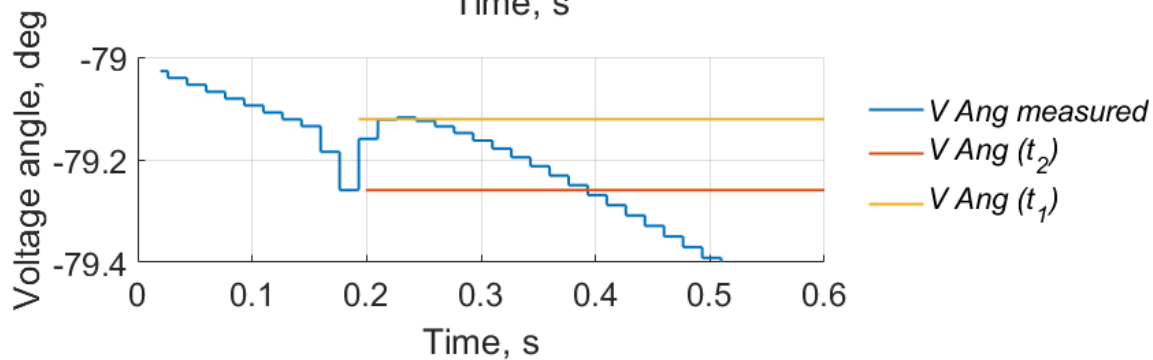
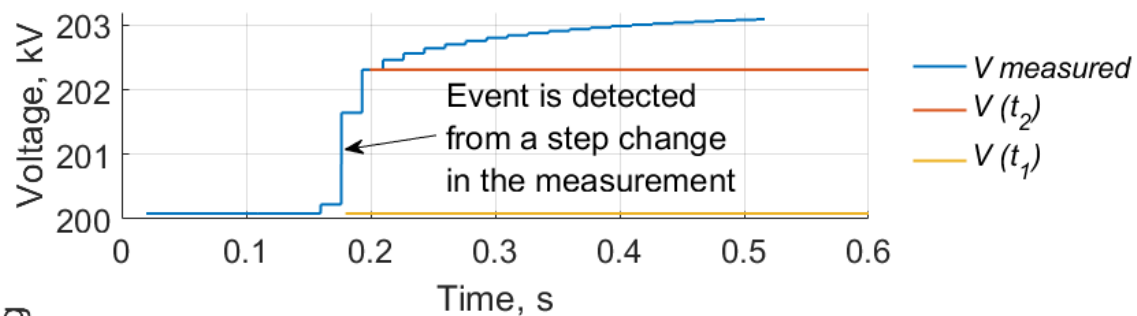
- How it works?
- The goal is to develop an easily implementable out-of-step tripping algorithm that is adaptive in real-time and requires minimal settings.
- The developed algorithm relies on the computation of system impedances seen from remote ends of a transmission line.
- To compute the system impedances on seen from the remote ends of transmission lines the following equation is used [1]:

$$\underline{Z}_{eq} = \frac{\underline{V}(t_2) - \underline{V}(t_1)}{\underline{I}(t_2) - \underline{I}(t_1)} = -\frac{\underline{\Delta V}}{\underline{\Delta I}}$$



# The new adaptive algorithm (1)

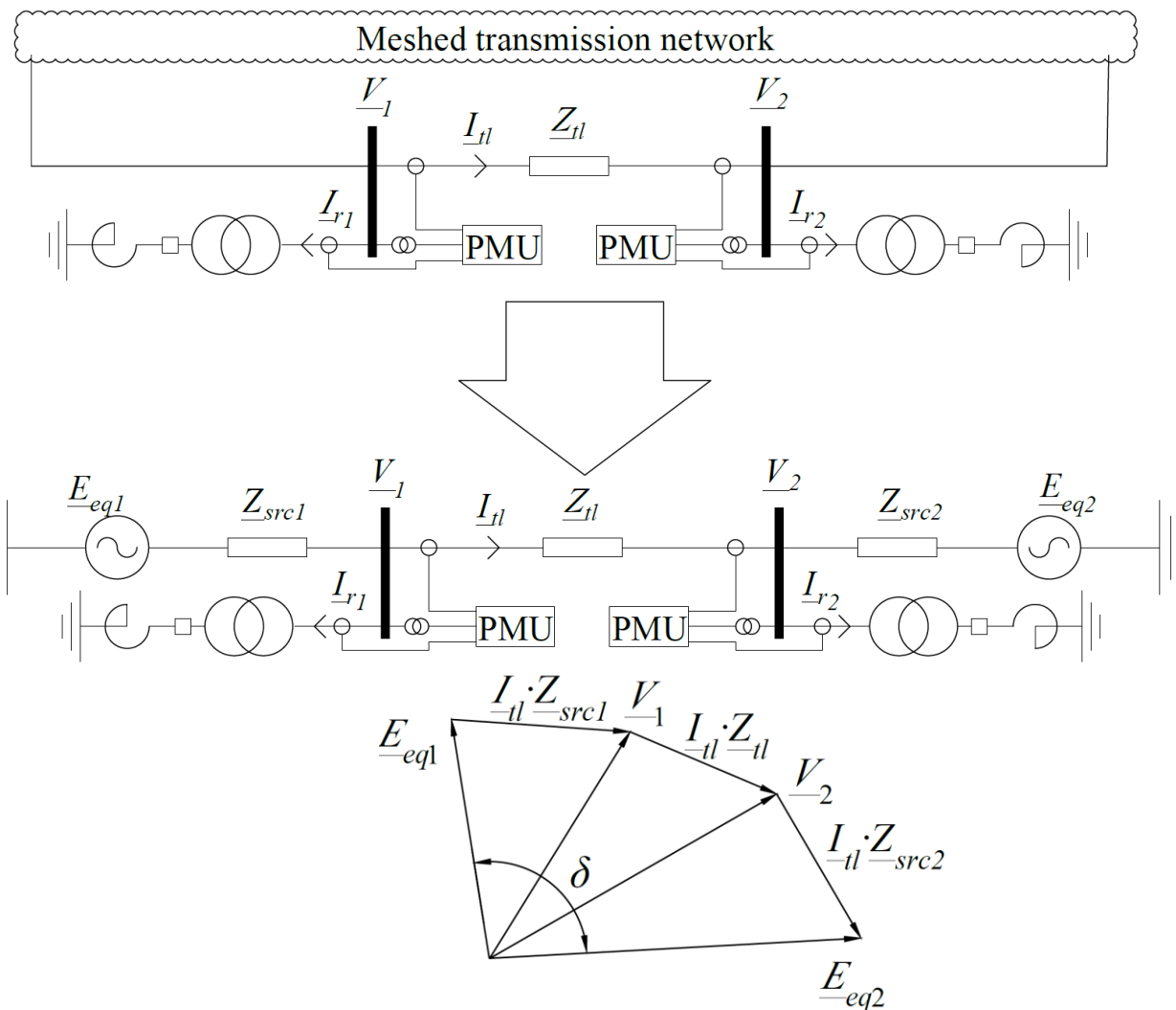
- How it works?



# The new adaptive algorithm (2)

- How it works?
- Full system impedance is computed on the bus and reduced to only  $\underline{Z}_{src}$  on both ends of the transmission lines by using the following formula:

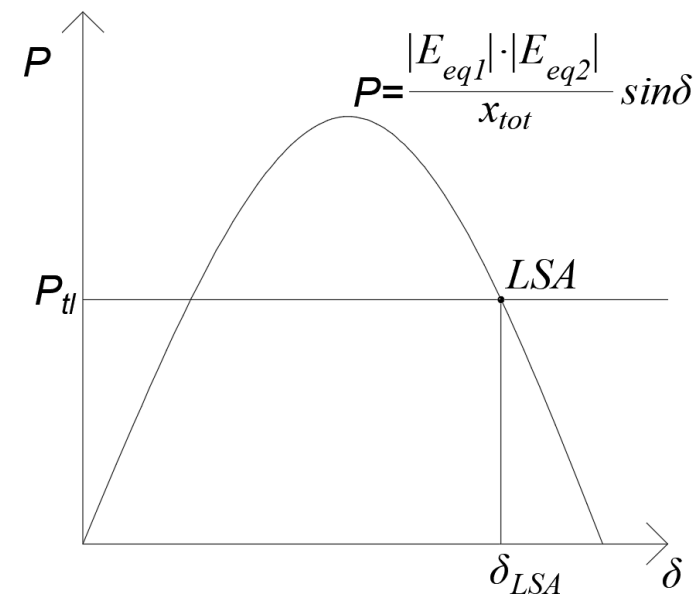
$$\underline{Z}_{src1} = - \frac{V_1(t_2) - V_1(t_1)}{I_{r1}(t_2) - I_{r1}(t_1)} \cdot \frac{I_{r1}(t_1) - I_{r1}(t_2)}{I_{tl}(t_1) - I_{tl}(t_2)} = \frac{\frac{\Delta V_1}{\Delta I_1} \frac{\Delta I_{r1}}{\Delta I_{r1} - \Delta I_{tl}}}{\frac{\Delta V_1}{\Delta I_{r1} - \Delta I_{tl}}}$$



# The new adaptive algorithm (3)

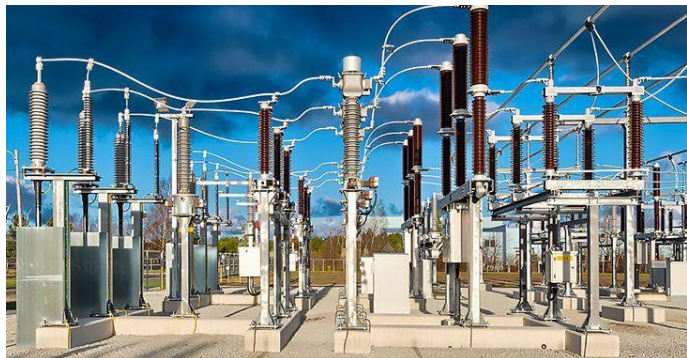
- How it works?
- From computed system impedances a power-angle curve is built.
- On power-angle curve the last stable angle is fixed by using the computed angle difference between the sources ( $90^\circ < LSA < 130^\circ$ ).
- The angle  $\delta$  between two equivalent sources is computed using measured voltages and currents and computed impedances.
- Operation criteria:

$$\left\{ \begin{array}{l} \delta > \delta_{LSA} \text{ for two consecutive measurements} \\ \frac{d\delta}{dt} > 0 \text{ for two consecutive measurements} \\ V_1 > 0.5 \text{ pu} \\ V_2 > 0.5 \text{ pu} \\ \frac{d\delta}{dt} < 20\pi \text{ rad for two consecutive measurements} \end{array} \right.$$





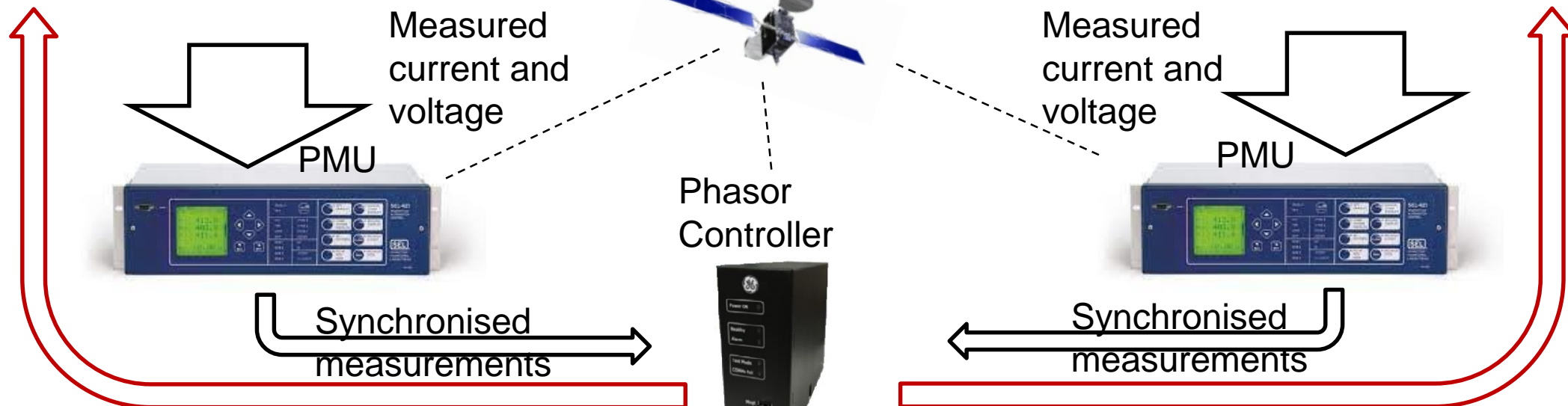
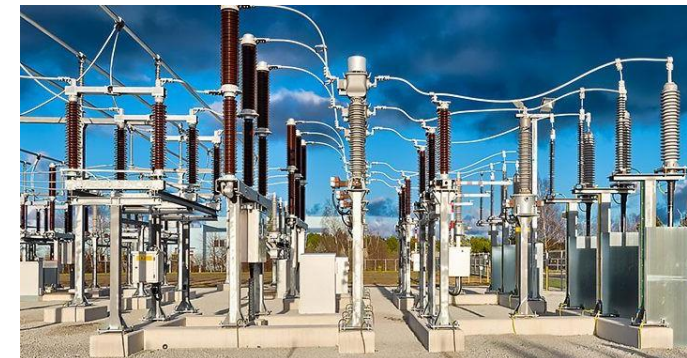
# Real-world? Substation 1



# Transmission network



# Substation 2



Commands to circuit breakers in a substation

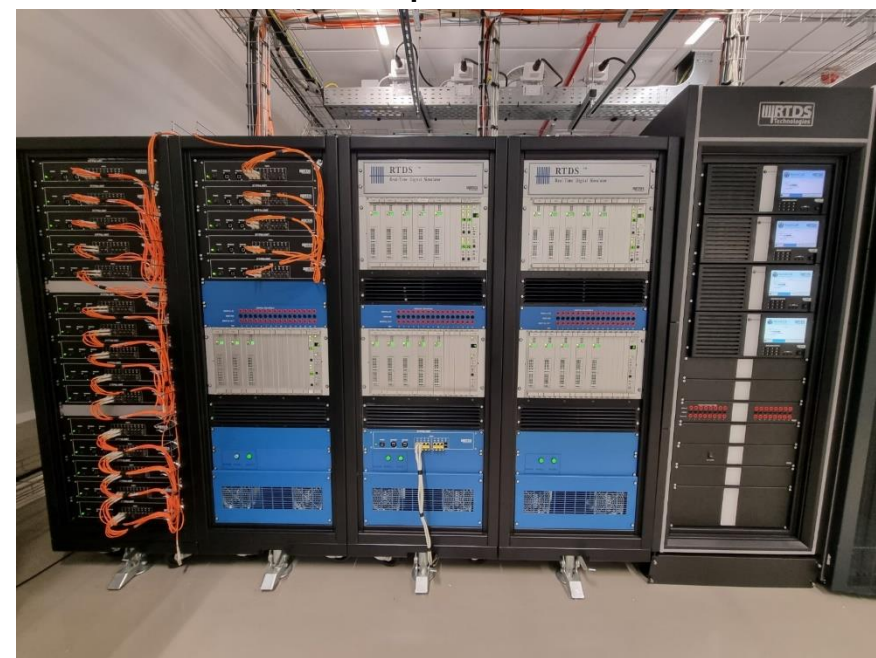
Commands to circuit breakers in a substation



Out-of-step detection algorithm

# HiL test setup

RTDS setup at TUDelft



IRIG-B time signal

Meinberg Syncbox



PTP time signal

Seven Solutions atomic clock slave unit



GTFPI interface



Trip signals to HV panel

GTAO output card



$\pm 10V$  analogue signal



Power amplifier

$\pm 100V$  analogue signal



Impedance-based protection relays

GTNETx2 card



C37.118 data

IEC 61850 data



C37.118 data

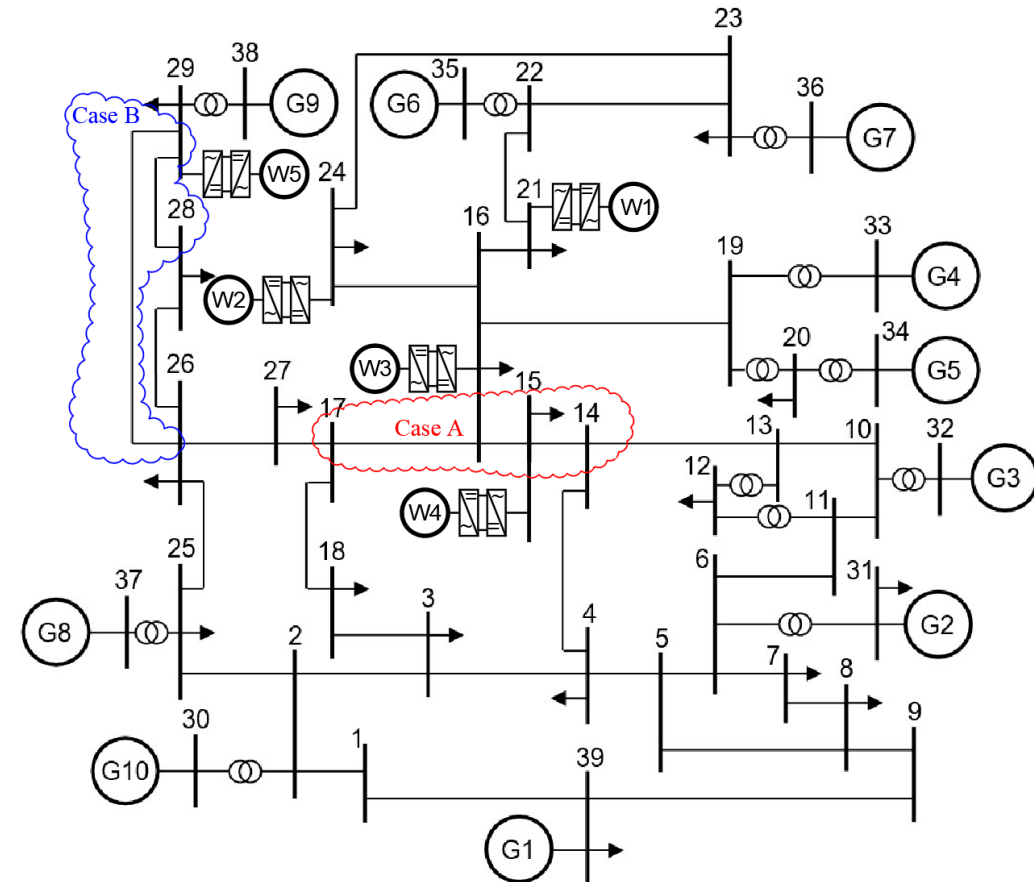
IEC 61850 data



External controller with running the developed algorithm

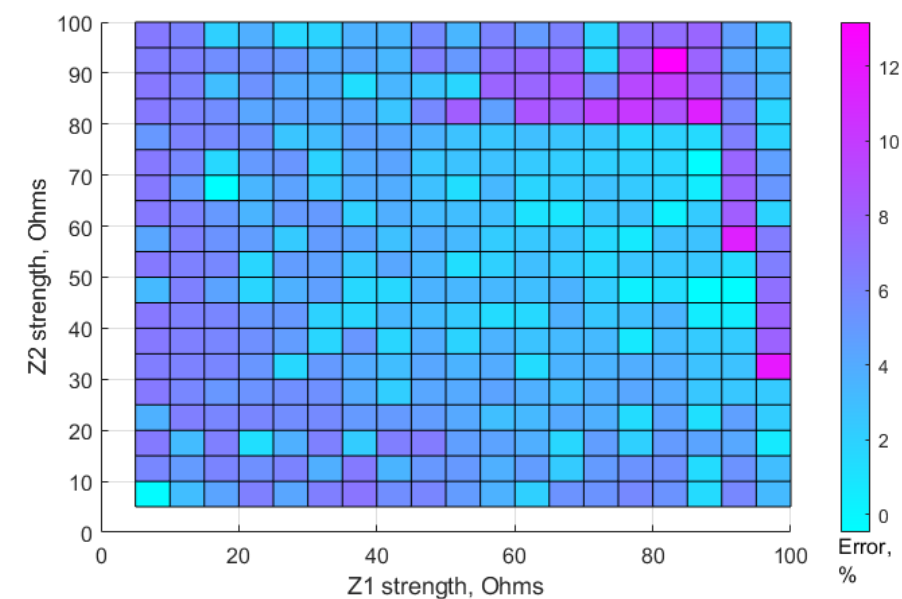
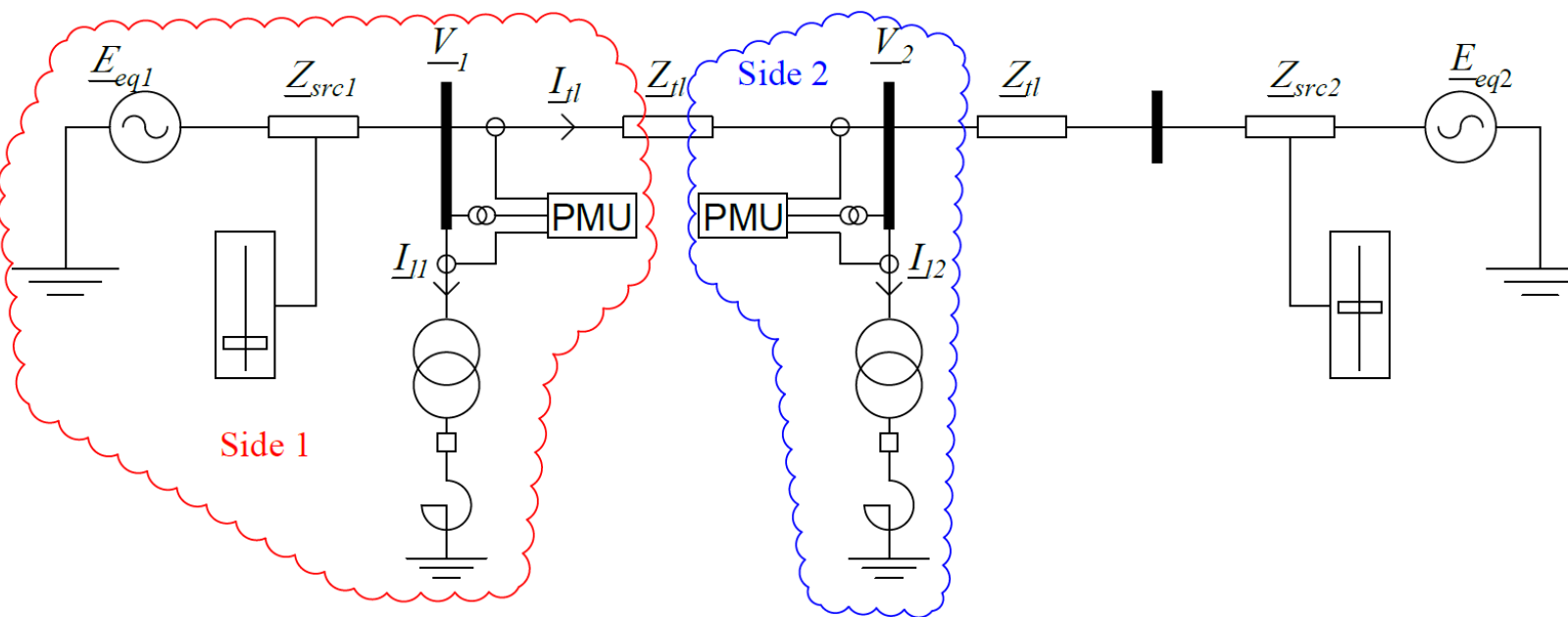
# Hil test setup

- Test network
- IEEE 39 bus benchmark system is taken as a basis for larger system studies to investigate the out-of-step protection performance.
- Implementation of wind power plants into the network.
- Two scenarios are demonstrated in the network:
  - Case study A, in red, to represent swings between two system parts.
  - Case study B, in blue, to represent swings between single machine – infinite bus.



# Testing results

- Impedance computation
- To test and validate the impedance computation part of the new algorithm a simple system was developed and the following results were obtained.

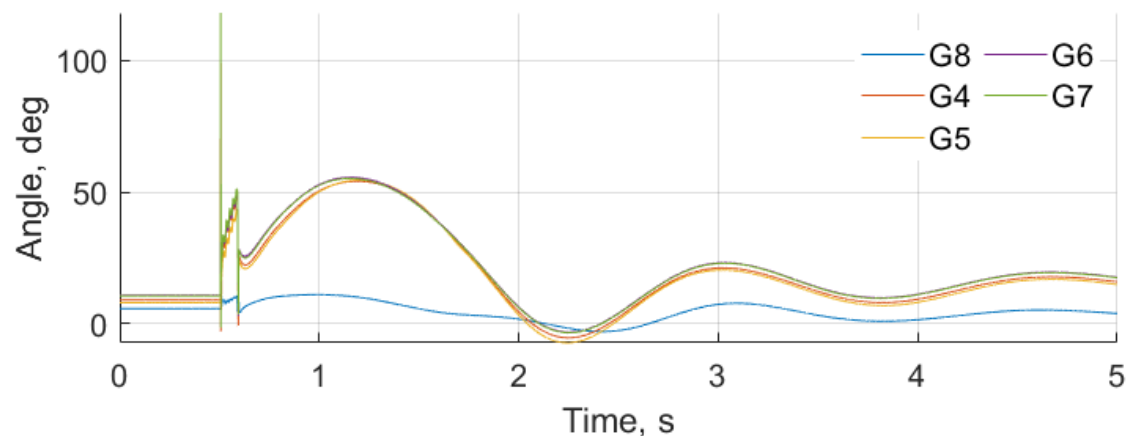




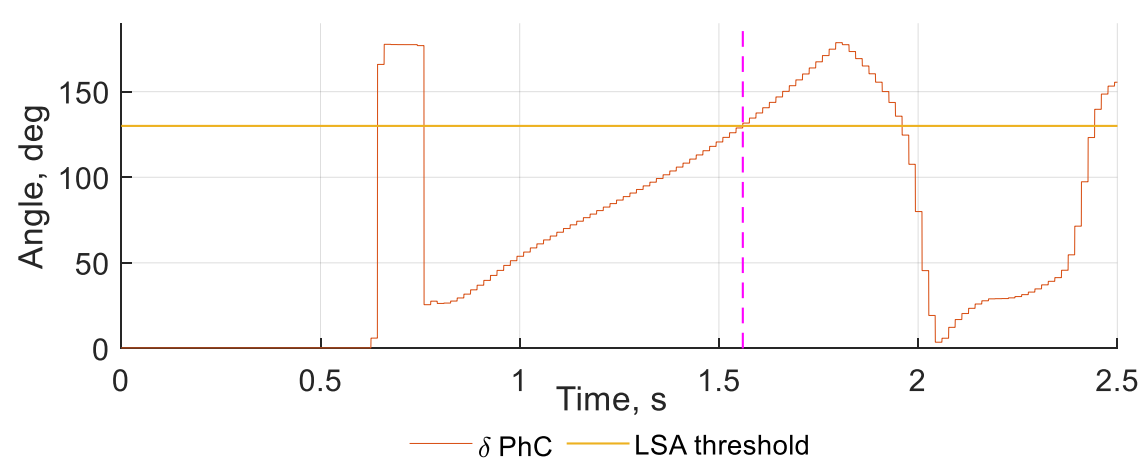
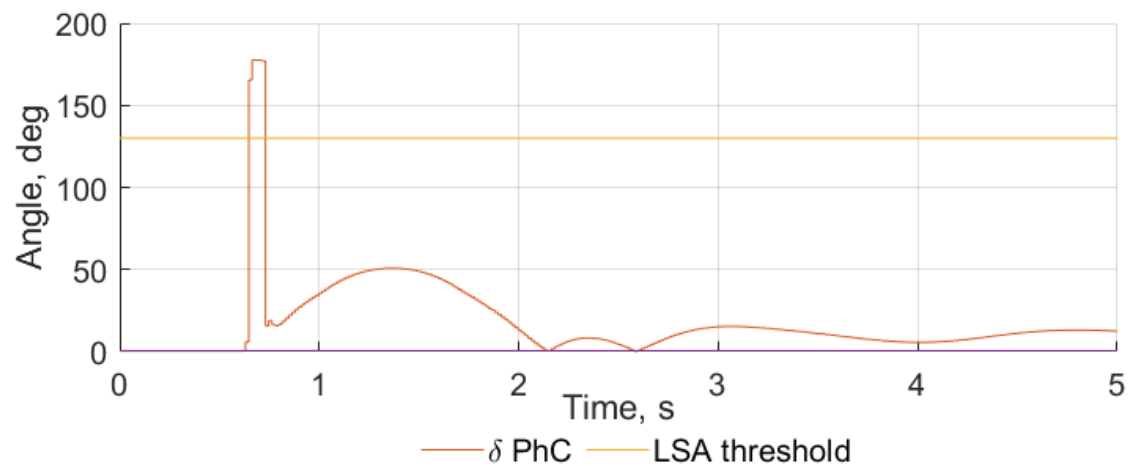
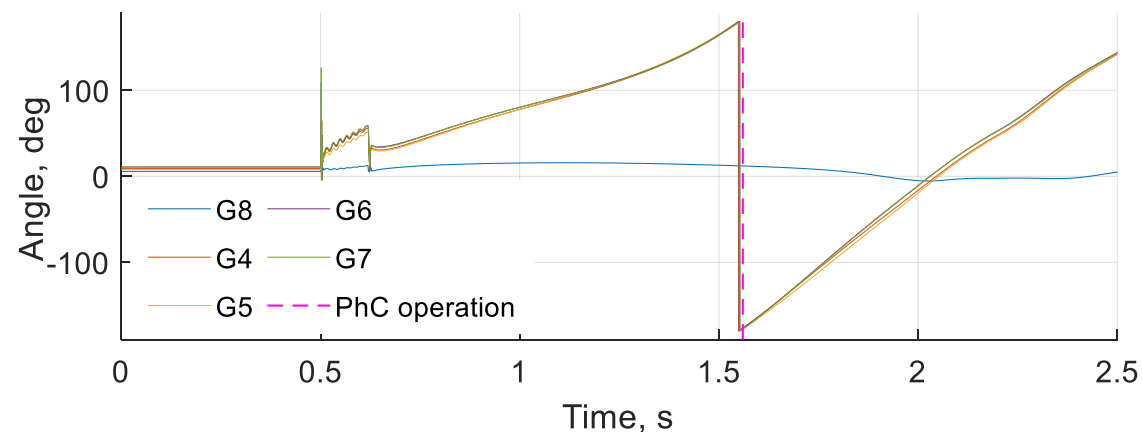
# Hil testing of the algorithm using RTDS (1)

- Algorithm behavior for stable and unstable power swings in the network

### Stable power swing



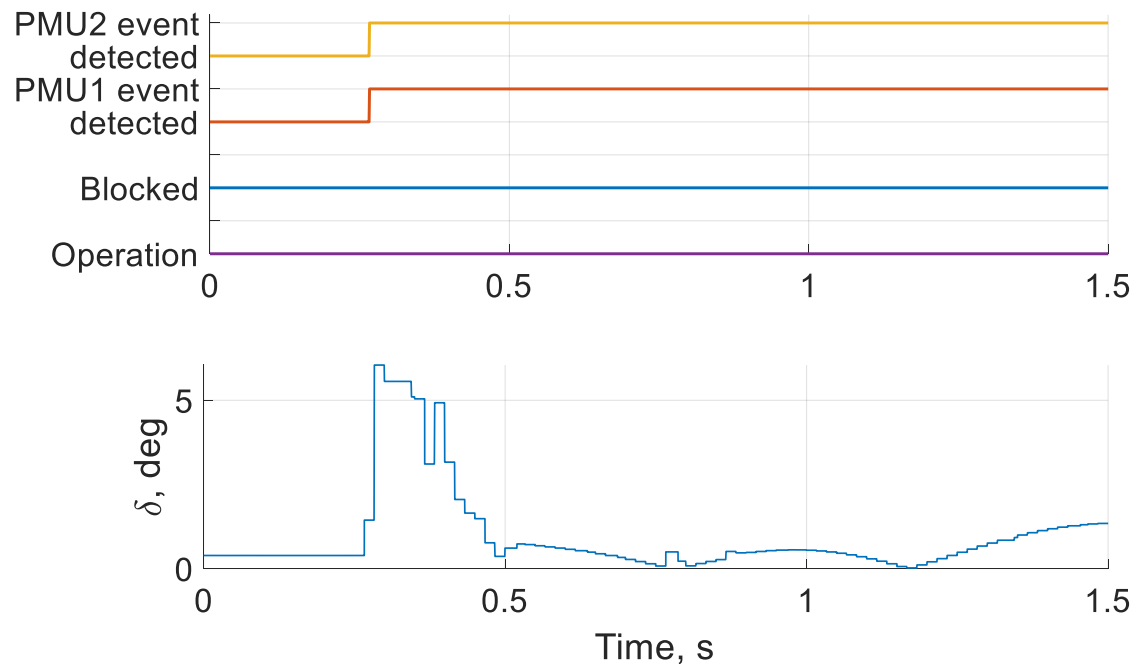
### Unstable power swing



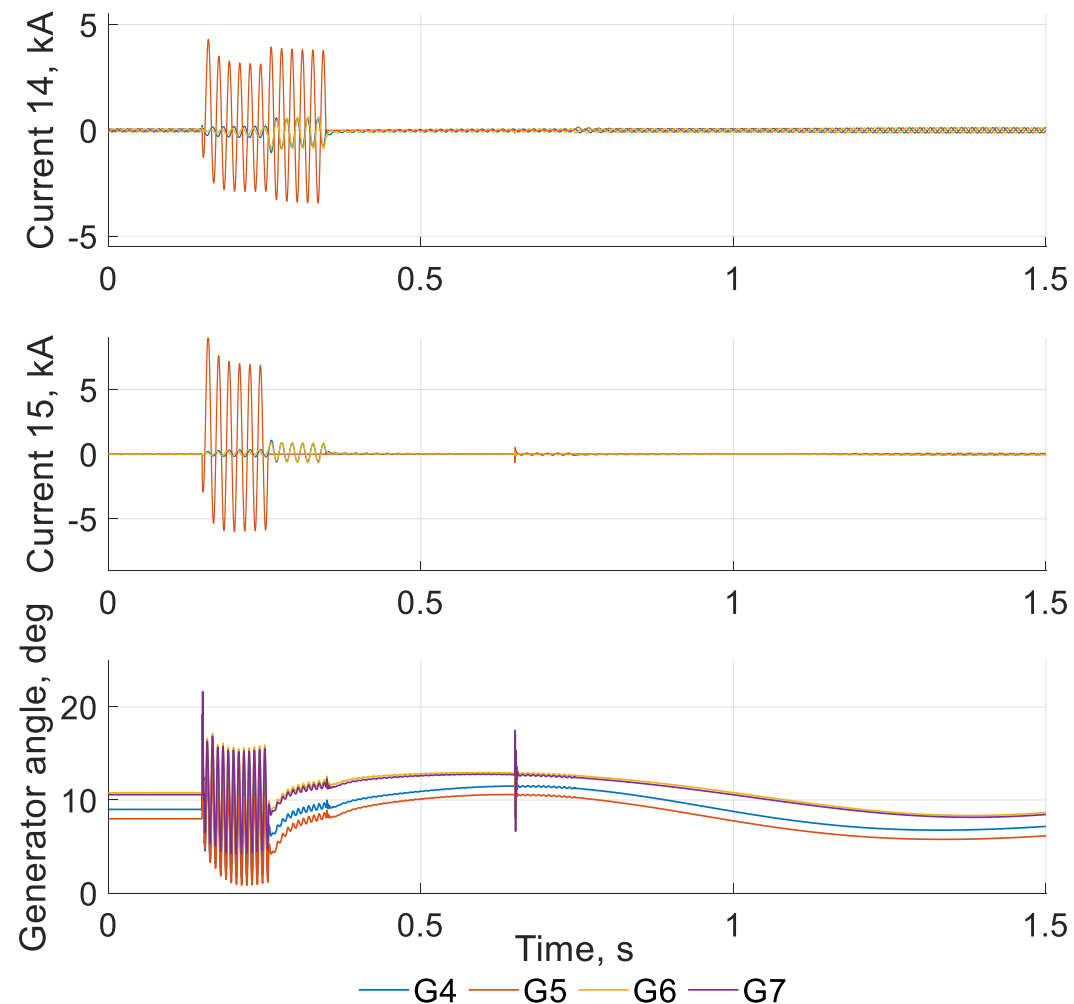
# Hil testing of the algorithm using RTDS (2)

- Algorithm behavior for grid events – SLG on protected line

### Algorithm signals from the controller



### Measured quantities

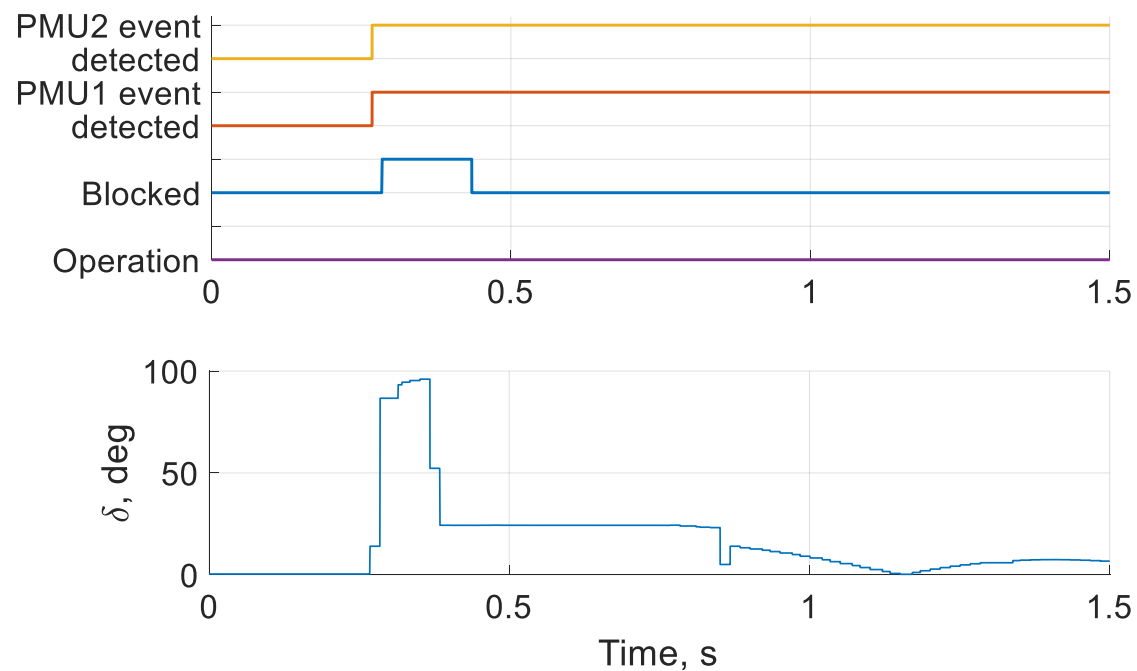




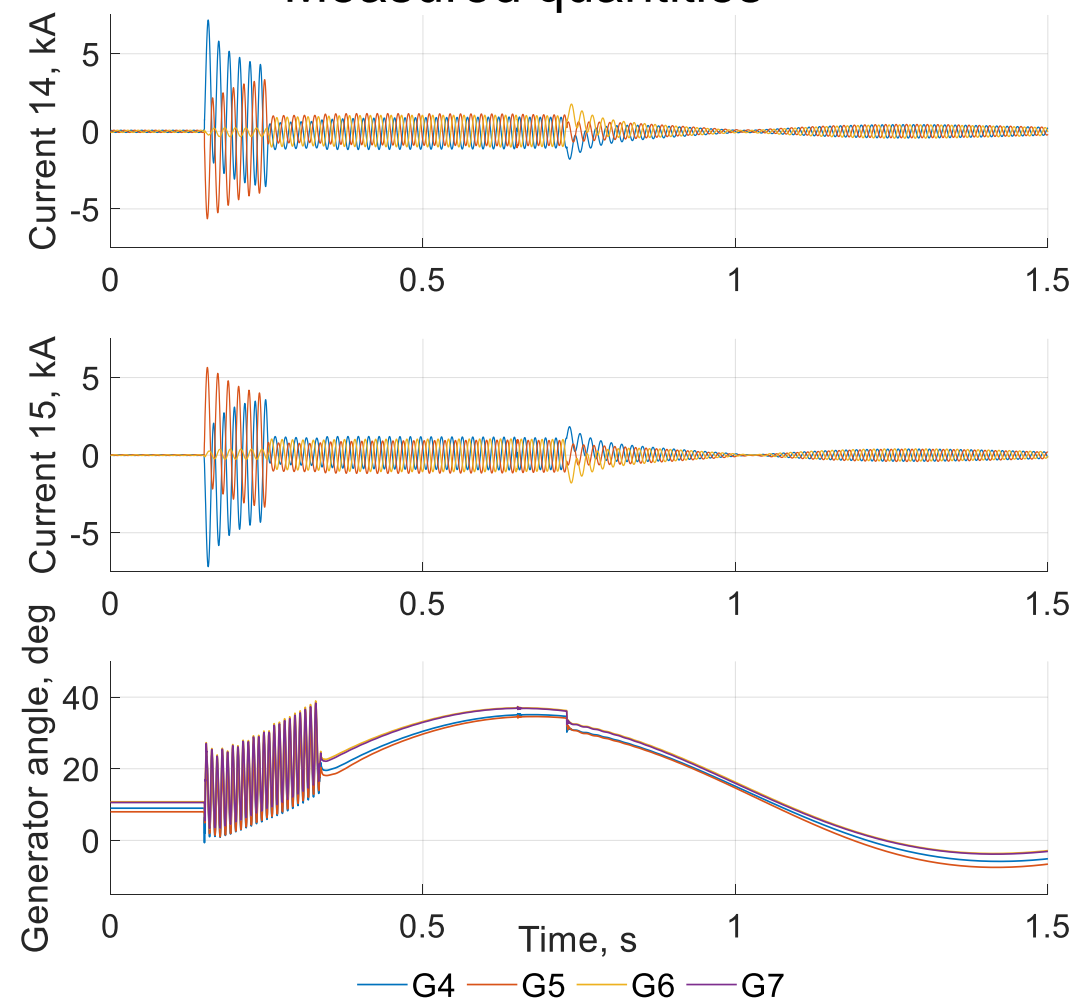
# Hil testing of the algorithm using RTDS (3)

- Algorithm behavior for grid events – LL outside of the protected line

### Algorithm signals from the controller



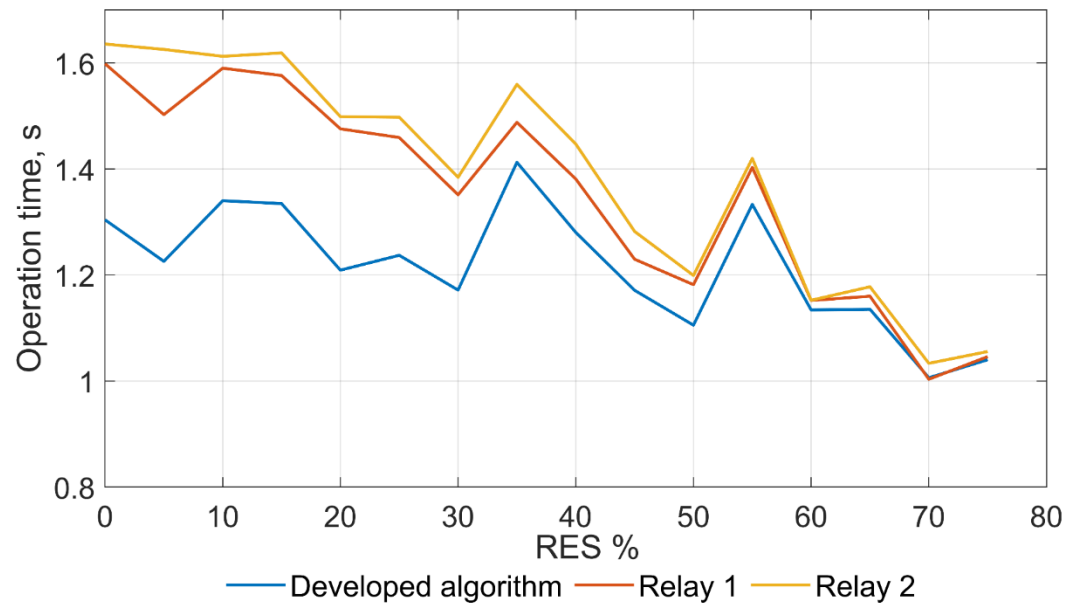
### Measured quantities



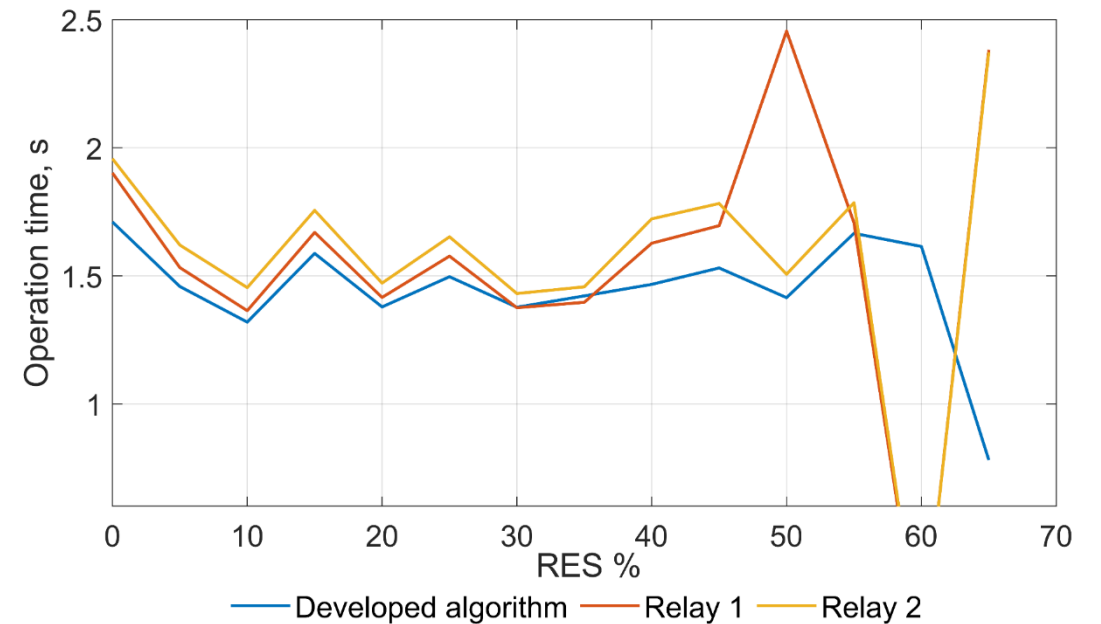
# Hil testing of the algorithm using RTDS (4)

- Results for Case study A

### Longer transmission line



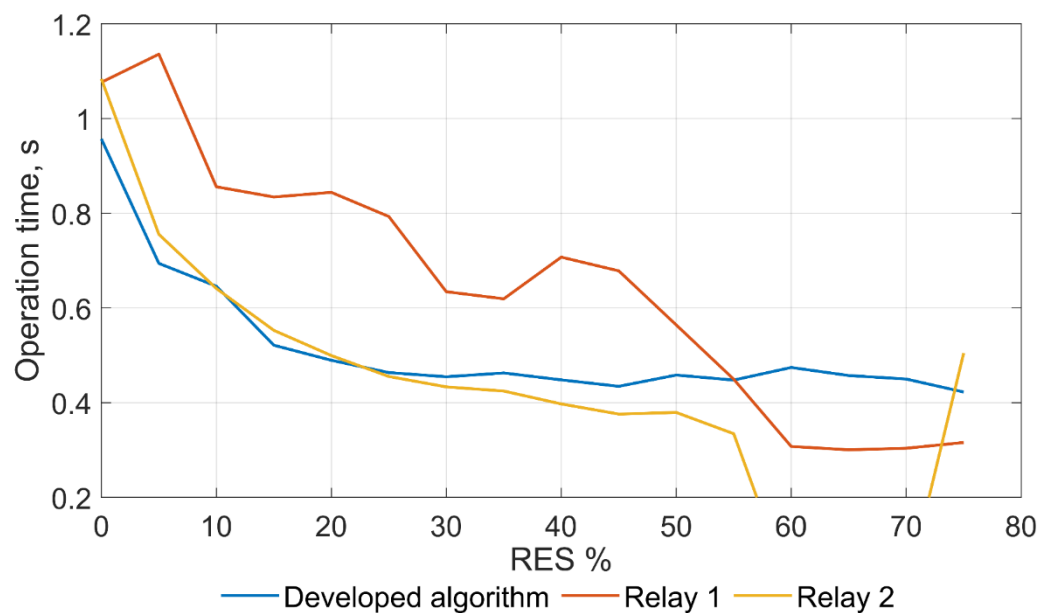
### Shorter transmission line



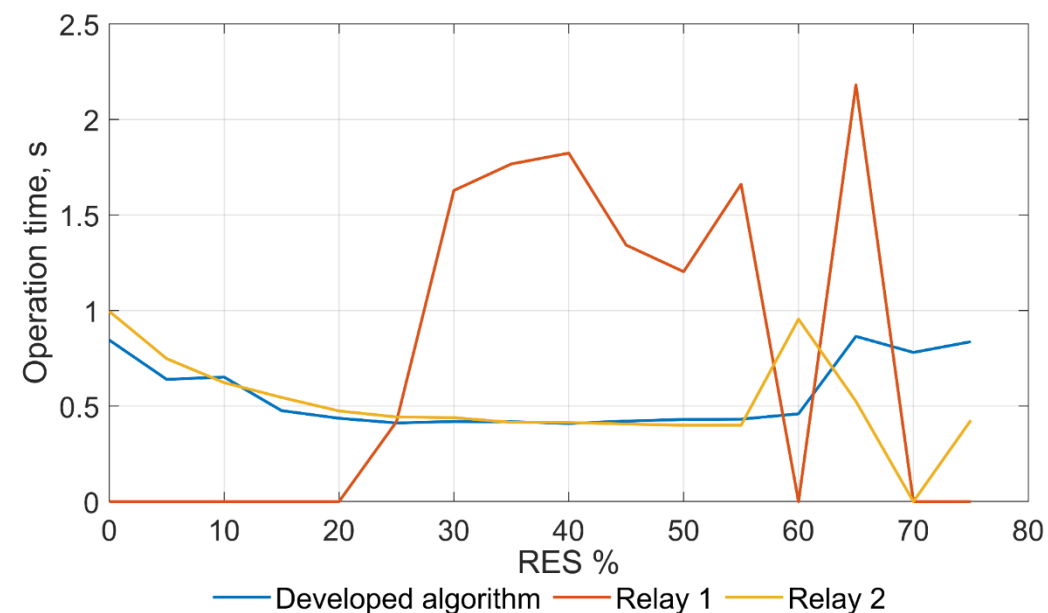
# Hil testing of the algorithm using RTDS (5)

- Results for Case study B

## Longer transmission line



## Shorter transmission line



# Contributors



Thank you for your attention

email: [M.Tealane@tudelft.nl](mailto:M.Tealane@tudelft.nl) / [marko.tealane@taltech.ee](mailto:marko.tealane@taltech.ee)